3-2. REPLACEMENT OF THE PICK UP

[PRECAUTION BEFORE REMOVING THE PICK UP BLOCK 1

When disconnecting or connecting the connectors P1 and P2, make sure that the P.C board (on the PICK UP BLOCK) has been short circuited as shown in Fig. 3-2. Do not turn the electricity "ON" while the P.C board is short circuited.

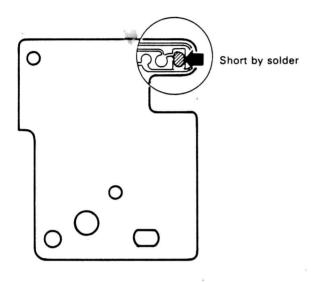
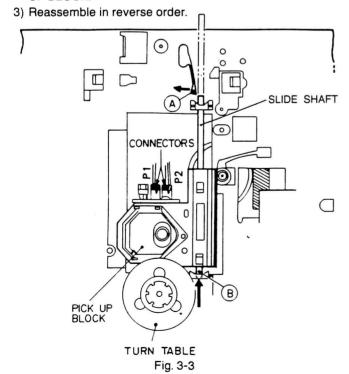


Fig. 3-2

- Disconnect the connectors P1 and P2 on the PICK UP BLOCK.
- Push the ® part of the pick up block SLIDE SHAFT and pull it in the arrowed direction to remove the PICK UP BLOCK.



3-3. REPLACEMENT OF THE SPINDLE MOTOR

- 1) Turn the A GEAR HOLDER LEVER counter-clockwise (Fig. 3-4), then pull out the SLIDE GEAR.
- 2) Keep the PICK UP BLOCK away from the SPINDLE MOTOR († direction as shown in Fig. 3-5).
- Remove the two SPINDLE MOTOR fixation screws through the hole on the TURN TABLE (Fig. 3-5), then remove the SPINDLE MOTOR.
- 4) Reassemble in reverse order.

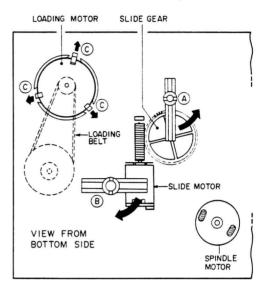


Fig. 3-4
PICK-UP BLOCK
VIEW FROM UPPER SIDE
SCREW
TURN TABLE

Fig. 3-5

3-4. REPLACEMENT OF THE LOADING MOTOR

- 1) Remove the LOADING BELT, then remove the LOAD-ING MOTOR while releasing the © hooks (Fig. 3-4).
- To reassemble, push in the LOADING MOTOR and replace the LOADING BELT.

3-5. REPLACEMENT OF THE SLIDE MOTOR

- 1) Turn the ® SLIDE MOTOR HOLD LEVER (Fig. 3-4) clockwise, then pull out the SLIDE MOTOR.
- 2) Reassemble in reverse order.

V. REPLACEMENT OF SPINDLE MOTOR

5-1. REMOVE AND ASSEMBLY SPINDLE

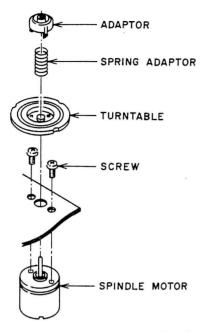


Fig. 5-1

- 1) Pull out the turntable, Spring adaptor and Adaptor.
- 2) Remove two Screws.
- 3) Unsolder two Spindle Motor wires.
- 4) Solder two wires to the new Spindle Motor.
- Put the new spindle Motor on the chassis with two screws
- 6) Press-in the turn table on to the Motor shaft.

 Adjust the turntable so that the hight of the turntable from chassis become 6.6 ± 0.1 mm (Fig. 5-2).

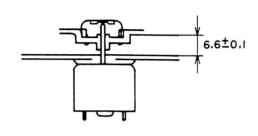
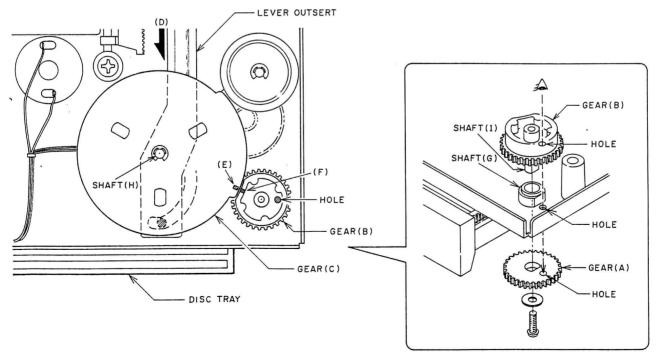


Fig. 5-2

VI. HOW TO INSTALL OF THE LOADING MECHANISM

- 1. Set the Disc Tray in a loading condition.
- 2. Set the gear (B) on the shaft (G).
 When the gear (B) is set properly, fit the Hole of the gear (B) to the hole of the CHASSIS. (Fig. 6-1)
- 3. Press the Lever-outsert to fully direction (D). (Fig. 6-1)
- Set the gear (C) on the shaft (H).
 When the gear (C) is set properly, fit the MARK (E) to the MARK (F). (Fig. 6-1)
- 5. Set the gear (A) on the shaft (I).

 When the gear (A) is set properly, fit the Hole of the gear (A) to the Hole of the CHASSIS. (Fig. 6-1)



F1g. 6-1

7-1. ADJUSTMENT WHEN CHANGING THE PICK-UP

7-1-1. Pick-up Inclination Adjustment

Fine inclination adjustment in the jitter direction is necessary after replacing the pick-up. Adjustment is performed by rotating the Jitter Direction Inclination Adjustment Screw. (Fig. 7-1)

- 1) Connect the oscilloscope between J202 pin (3) (HF signal) and GND.
- 2) Set the unit in the TEST MODE 4.

NOTE: "How to make test Mode" has been written in the Servo Adjustment Procedure.

- 3) Press the (FF)/(RF) Buttons so that the Jitter Direction Adjustment Screw may situate to the middle of the Inclination Adjustment Hole. (Fig. 1-1)
- 4) Confirm that the HF signal (Eye-Pattern) shown in Fig. 7-2.
- 5) Turn right and left the Jitter Direction Adjustment Screw (Fig. 7-1) with the hexagonal driver (2.4 mm) until the HF Signal pattern change from (A) to (B) in Fig. 7-3.
- 6) After adjustment confirm that the HF signal level is within the range indicated below.

Check that the HF signal pattern is clear as shown in Fig. 7-3 \boxed{B} .

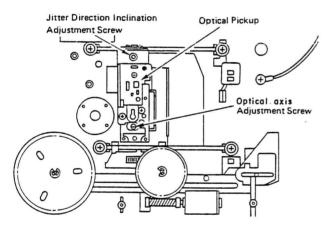


Fig. 7-1

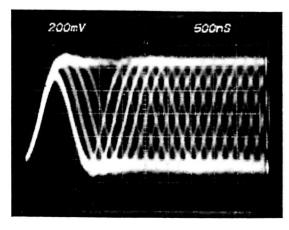
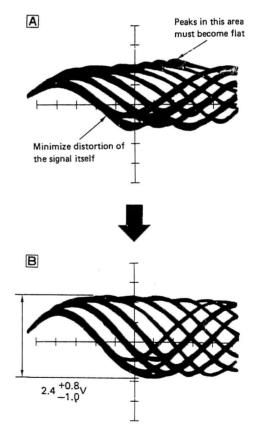


Fig. 7-2



(A): HF Signal before jitter direction adjustment (B): HF Signal after jitter direction adjustment

Fig. 7-3

7-1-2. Optical Axis Adjustment

If the mechanical eccentricity is large when fixing the pick-up tracking errors become large.

This is turn interferres with the tracking servo, so optical axis adjustment is necessary.

- 1) Set the unit in TEST MODE 3.
- 2) Press the (FF)/(RF) Button so that the optical axis adjustment screw situate to the middle of the optical axis adjustment hall. (Fig. 1-1, Fig. 6-1)
- 3) Connect the oscilloscope between J202 pin ② and GND.
- 4) Adjust the optical axis adjustment screw so that T.E (Truck Error) signal becomes maximum. (Fig. 7-4)

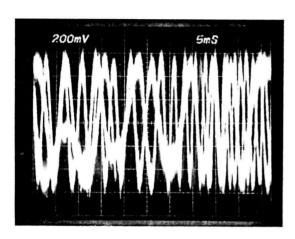


Fig. 7-4

7-1-3. Readjustment of E-F Balance

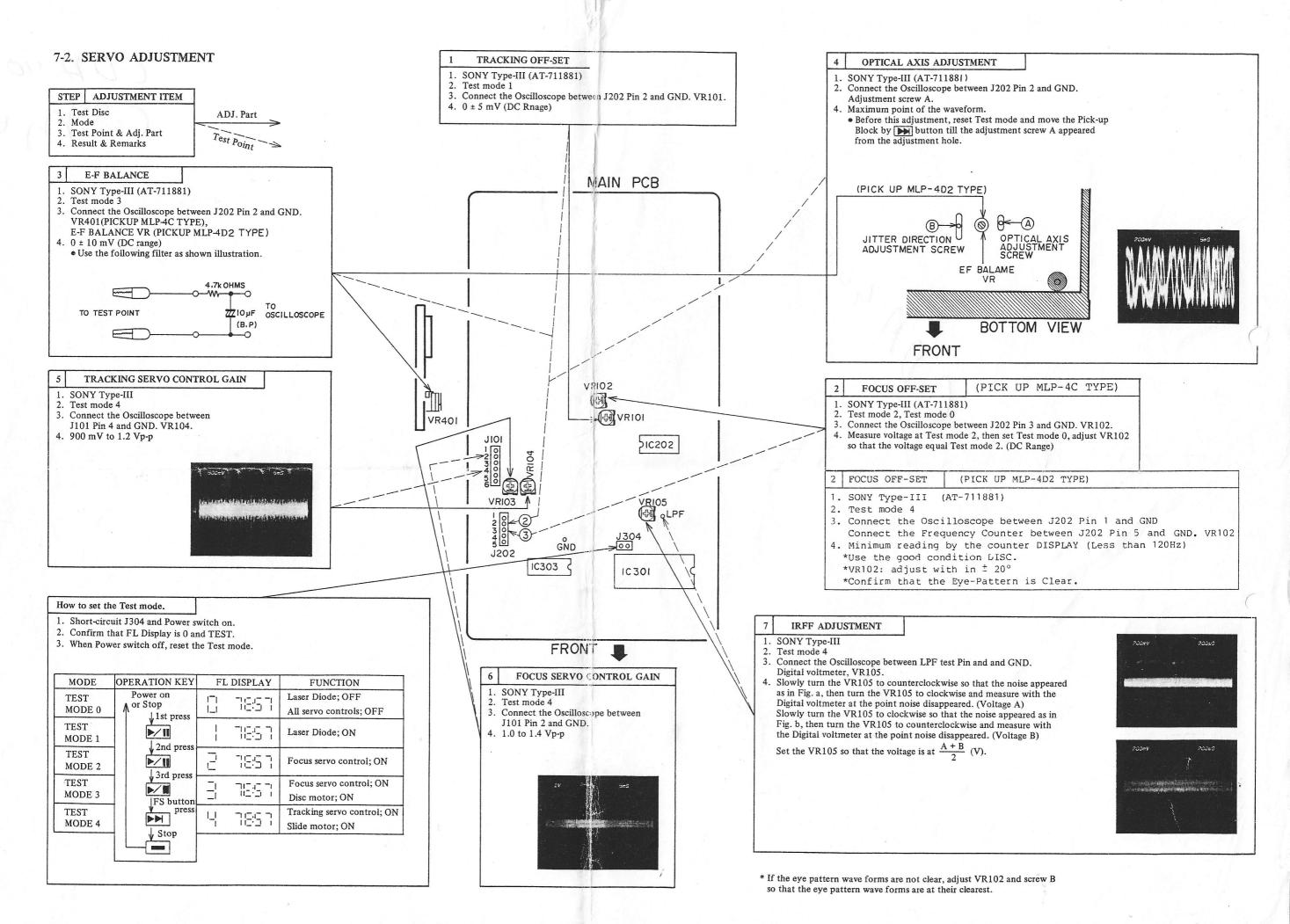
When the pick-up is changed. E-F balance adjustment must be performed. Refer to 7-2 Servo adjustment.

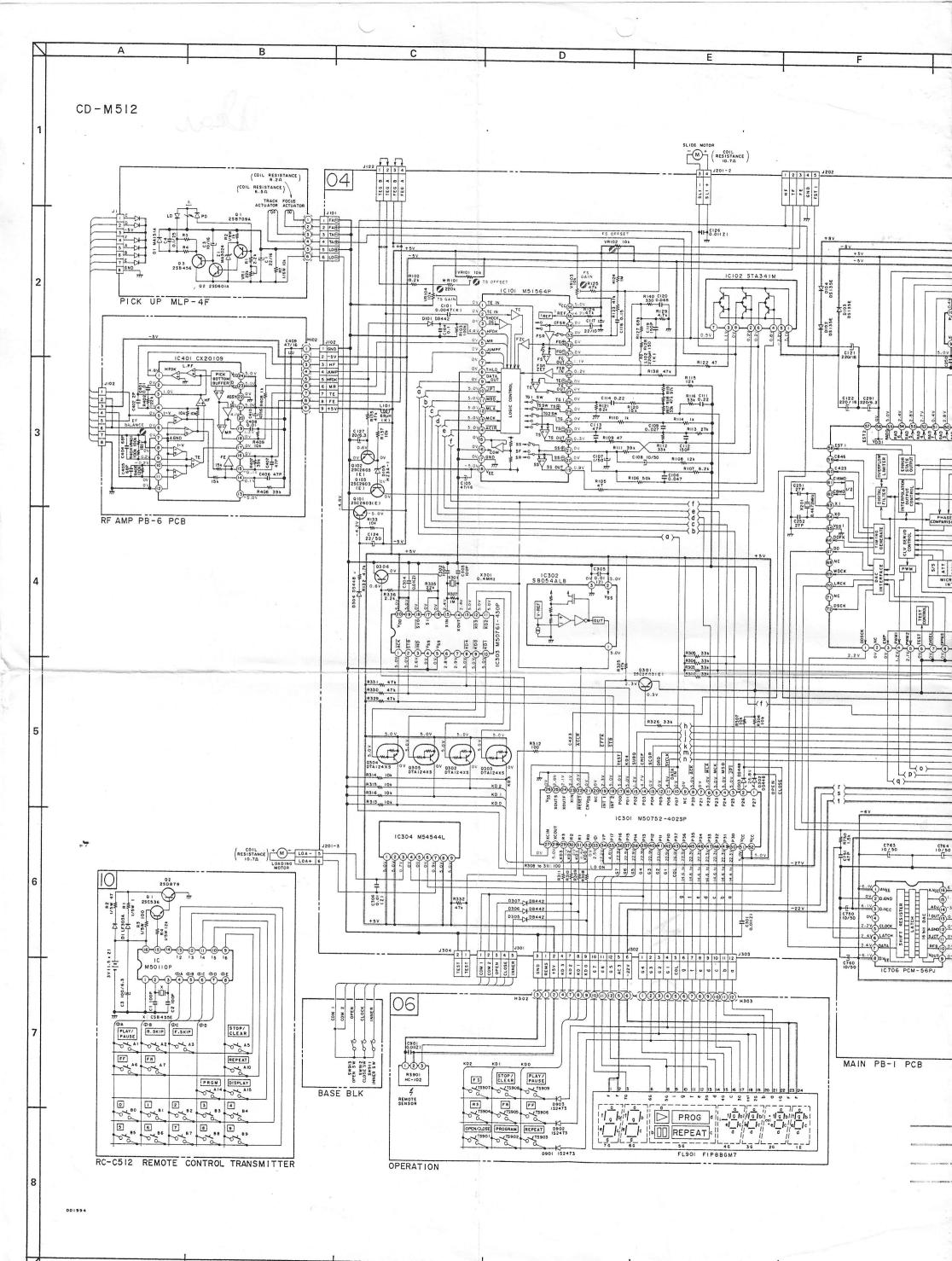
7-1-4. APC (Automatic Power Control) Circuity

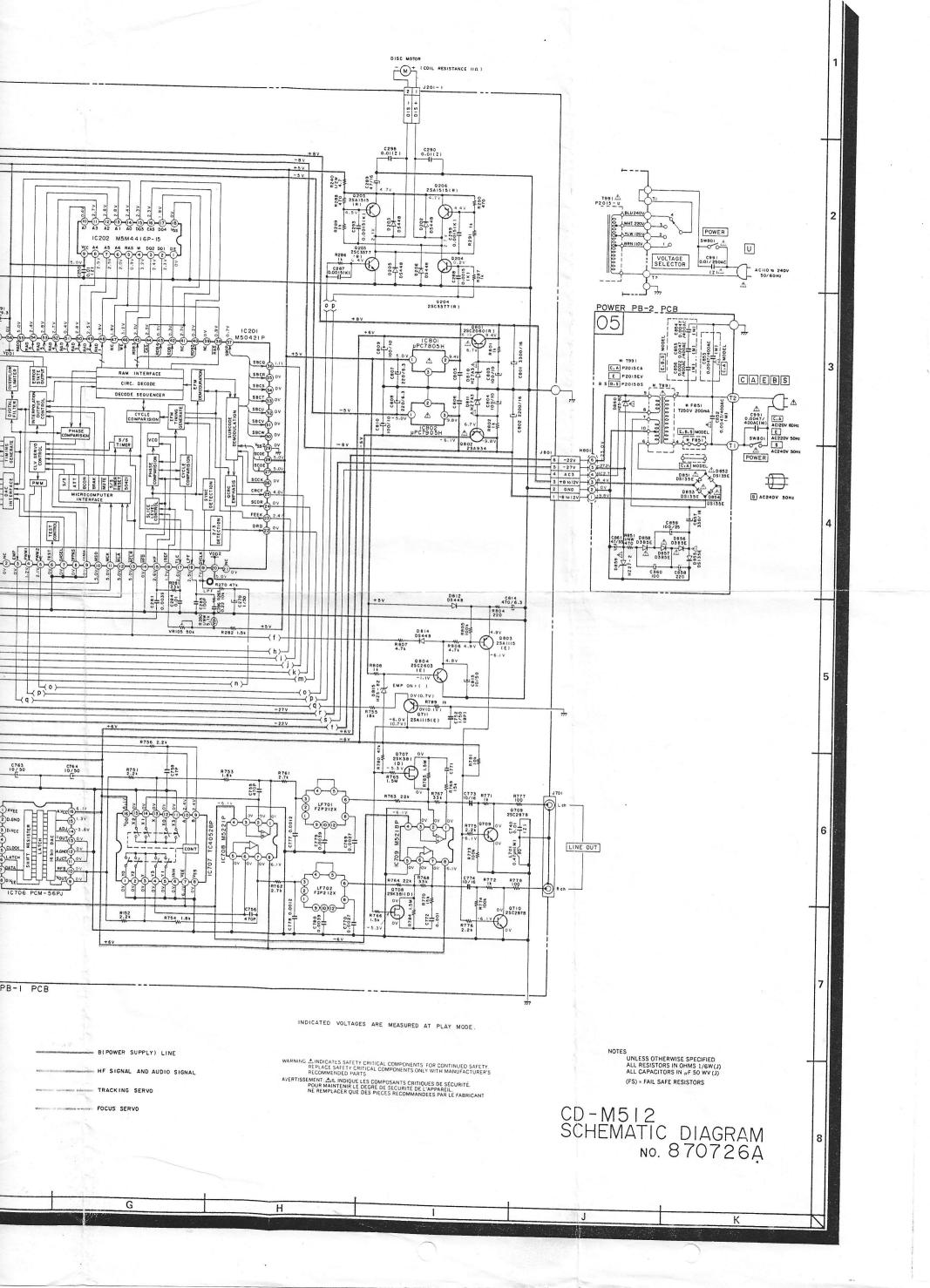
This is a servo circuit to maintain the LD (Laser Diode) power of the pick-up. The LD power can be adjusted by the VR1 by the pick-up block. However appropriate adjustment for individual characteristics has already been made so, DO NOT touch this.

NOTE:

It is required to adjust Servo control circuit when pick-up is replaced. Adjust the circuit according to the (7-2) Servo adjustment.







WARNING